

15.053 Exam 2 Notes

Linear Programming – The End

- Sensitivity analysis
 - *Relaxing or removing/tightening or adding* constraints makes *more/less* solutions available. This can be done by modifying the LHS or RHS.
 - Similarly *adding/removing* variables makes *more/less* solutions available.
 - *Less/more* feasible solutions means that the optimal value must stay the same or get *worse/better*.
 - It turns out, however, that this effect is **not** linear.
 - Changing an objective function coefficient will also change the result. It's also non-linear, but that's less obvious.
- LP Duality
 - Every LP has a dual, which characterises the sensitivity of the original solution.
 - One dual variable for each main LP constraint – **change in primal optimal value per unit increase in constraint RHS**.
 - In a way, it's the “fair price” of unit thing on the RHS of the constraint. We also call it the **marginal price** or **shadow price**.
 - Marginal/shadow price can be worked out from a simple linear program by increasing the RHS of a constraint by Δ , manually finding the new optimal solution, and seeing by how much it improves the objective function.
 - Marginal/shadow price can be worked out from a Simplex tableau. Simply work out the reduced cost for taking a slack variable into the basis, multiply it by -1 , and this gives the shadow price.

- Can also work out from Simplex tableau what range certain objective function coefficients can take before the current optimal solution stops being optimal.
 - Find every improving direction
 - Require that the reduced cost for every improving direction be **bad** – otherwise, the current optimal solution is no longer optimal, because we could go along the “good” directions.

- Constructing the dual

- Consider an LP with n variables, m constraints:

$$\begin{aligned} \min \quad & \sum_{j=1}^n c_j x_j \\ \text{s.t.} \quad & \sum_{j=1}^n a_{i,j} x_j \geq = \leq b_i \\ & x_j \geq = \leq 0 \end{aligned}$$

- The dual will have
 - One decision variable v_i for each constraint
 - Objective function $\max \sum_{i=1}^m b_i v_i$
 - For each **primal decision variable**, a constraint of the form

$$\sum_{i=1}^m a_{i,j} v_i \leq = \geq c_j$$

[Going “down the columns” of the primal problem]. The type of each constraint depends on the non-negativity constraint of the original variable.

- For each **dual decision variable**, make it \geq/\leq /free if the original inequality was $\geq/\leq/=$
- Swapping signs
 - **MINIMISATION PROBLEM:** keep signs of inequality going from *constraint* \rightarrow *non-negativity*, and flip the sign when going from *non-negativity* \rightarrow *constraint*.
 - **MAXIMISATION PROBLEM:** vice-versa.
- Strong duality – the optimal value of the primal and dual are the same.

- **Primal complimentary slackness** – *either* the optimal solution makes a main inequality constraint active *or* the corresponding dual variable has optimal value = 0. This reflects the fact that if something is not in short supply in the primal, its shadow cost is 0.
- **Computer output**
 - *Constraint sensitivity analysis* gives us
 - **Type** → $L \Leftrightarrow \geq$, $U \Leftrightarrow \leq$, $LU \Leftrightarrow =$
 - **Optimal dual** → optimal value of the dual variable corresponding to the constraint [= marginal]
 - **RHS coef** → the specified RHS coefficient in the original primal problem.
 - **Max increase/decrease** → the amount by which the RHS can be increased/decreased for which the dual solution remains valid.
 - *Variable sensitivity analysis*
 - **Optimal value** → optimal value of primal variable
 - **Bas Sts** → basic (B) or non-basic (NL/NU)
 - **Lower bound/upper bound/object coef** → specified stuff in the primal problem
 - **Reduced object** → |reduced cost of variable| at optimality. This is how much more attractive the variable's coefficient in the objective function must be before the variable is worth using.
 - **Max decrease/increase** → change of objective function coefficient for which primal optimal solution remains unchanged.

Games

- **0-sum game:** whatever someone wins, the other loses.
- **Pure strategy:** choose same thing every time. **Mixed strategy:** assign *probability* to each strategy.

- Want to **MAXIMIZE** *your* **MINIMUM** payoff or want to **MINIMIZE** *their* **MAXIMUM** payoff.
- Turns out these two aims/programs are **duals** of each other.

Graphs

- **Principle of optimality (for shortest path problem)** – in a graph with no negative dicycles (directed paths that start and end at the same node), optimal paths must have optimal subpaths.
- **Bellman-Ford algorithm**
 - Set $v = 0$ for the source, ∞ otherwise.
 - At each iteration, set v as the **minimum** of
 - Its previous value
 - For any node that leads into it, the v for that node + the length of the path that leads there.Set d to the neighbouring node that was used to work out v .
 - Terminate if
 - All the v s stay the same for one cycle
 - $t = n$ and they're not, which means there's a negative dicycle.
- The **critical path** is the **longest path through a graph**.